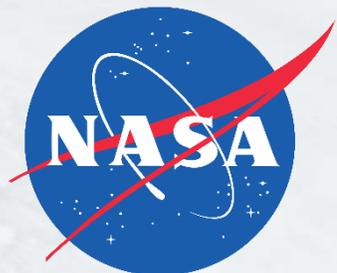


Overcoming the pixel: a nonlocal formulation of GPM passive MW precipitation retrieval

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UCIRVINE



An underdetermined inversion problem

The direct problem:

Hydrometeors
profile

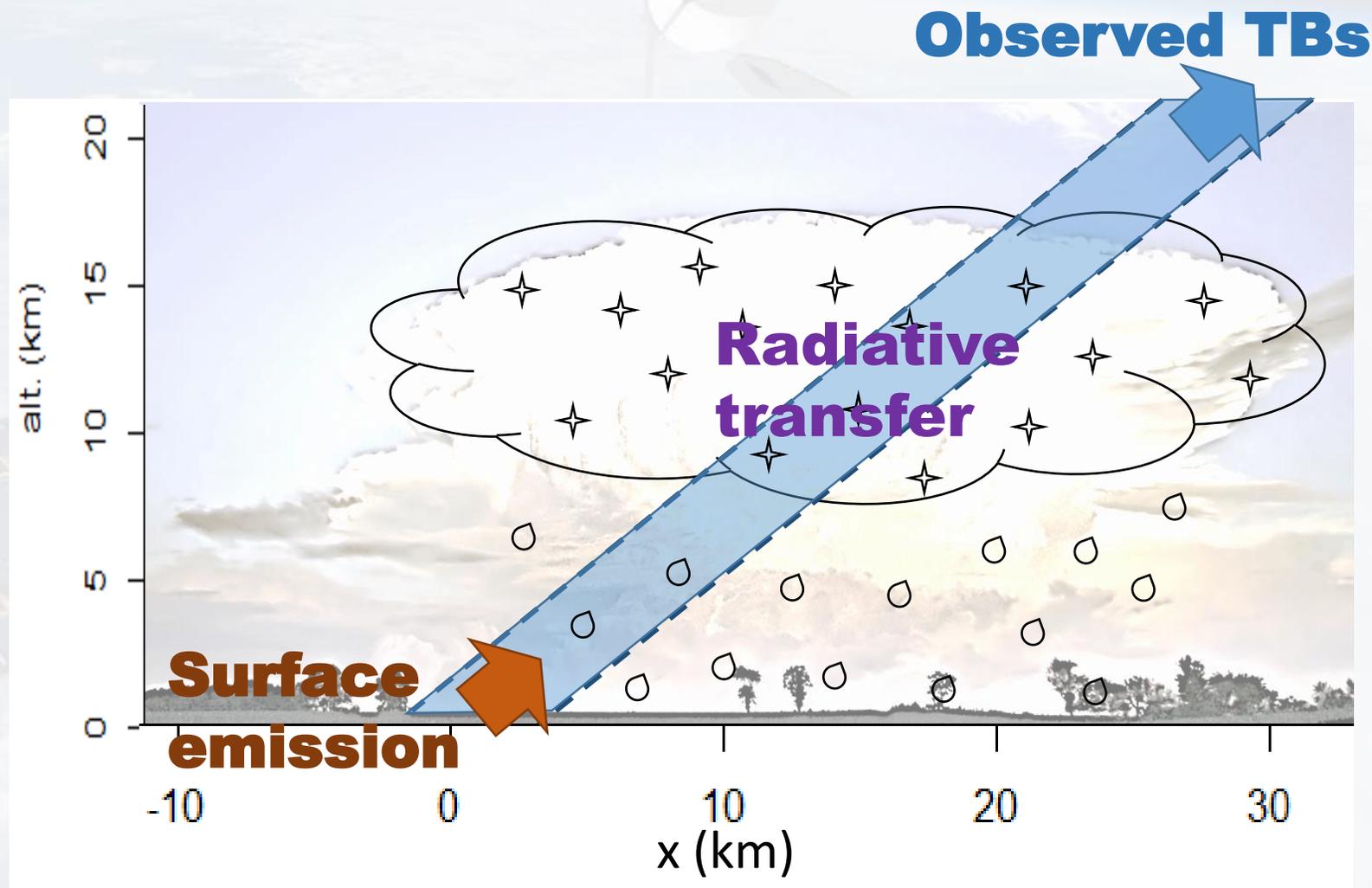
Surface
emissivity

$$TB = f(R_C, E_S)$$

Resolved by radiative transfer models.

The inverse problem:

$$R_C = g(TB, E_S)$$



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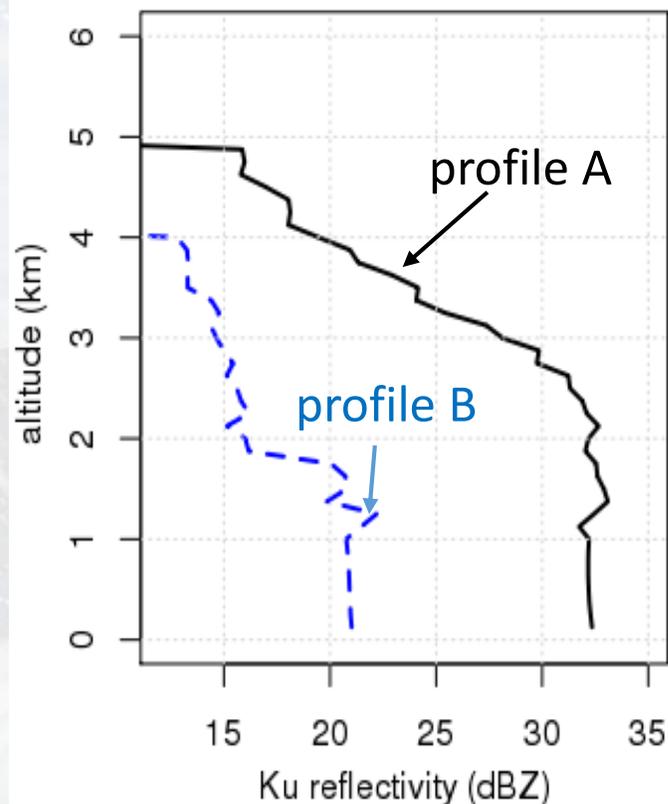
The inverse problem:

$$R_C = g(TB, E_S) \quad ?$$

Underdetermined

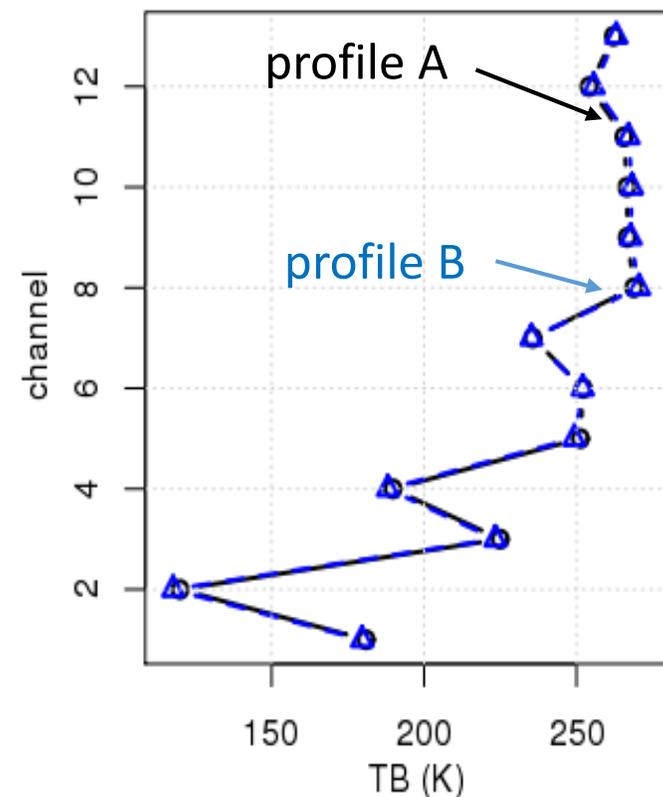


DPR Ku reflectivity



**Different hydrometeor
profiles**

GMI spectral signature



**Same spectral
signature**

Principle:

- Look for the solution among a set of previously observed atmospheric profiles: the **a-priori database**.
e.g.: GPM DPR profiles associated to observed (or simulated) TBs.
 - Select the appropriate profile based on the **radiometric distance** to the observation, i.e. a **vectorial distance in a N -dimensional space**, $N =$ number of channels, ($N = 13$ for GMI).
- ⇒ The retrieval becomes an **interpolation problem** in the N -dimensional radiometric space.

Retrieval as an interpolation problem:

The function $R(\overrightarrow{TB})$ to interpolate is irregular (in the Lipschitz sense):

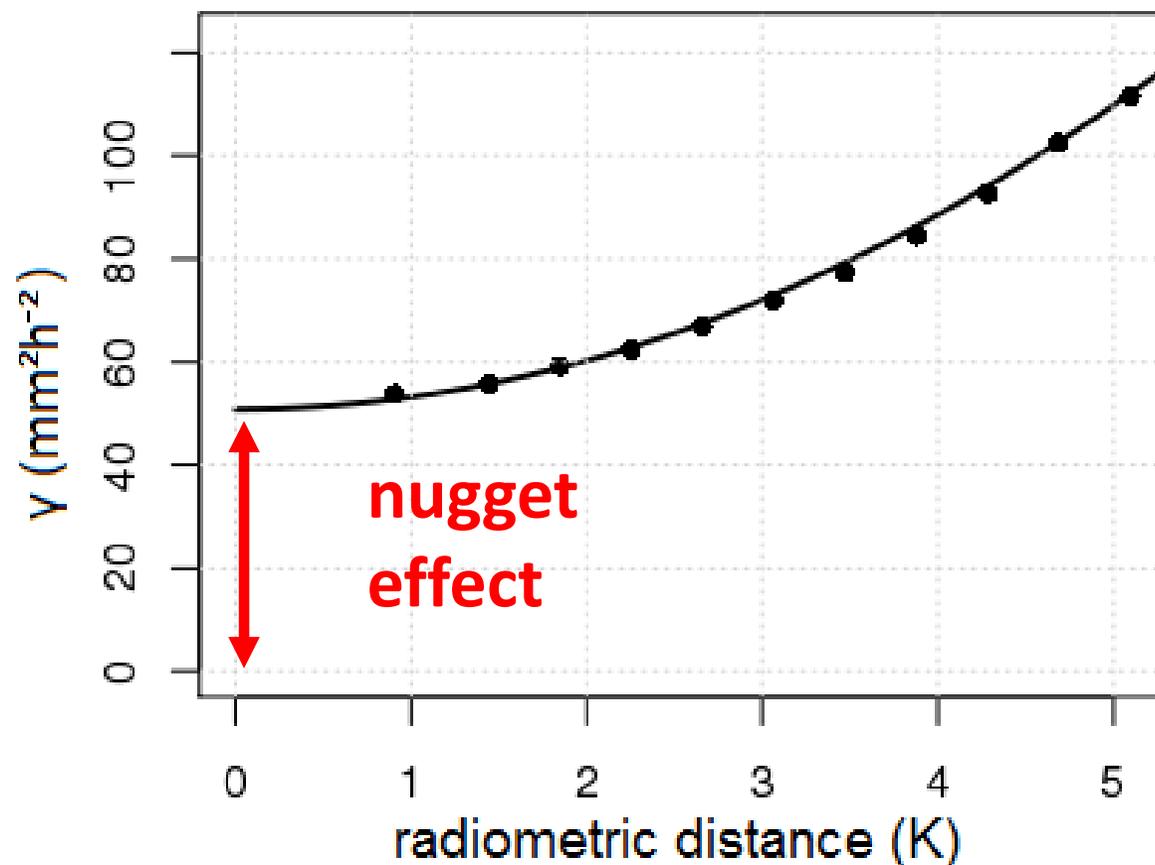
$$|\overrightarrow{TB}_1 - \overrightarrow{TB}_2| \rightarrow 0$$

does not necessarily imply that

$$|R(\overrightarrow{TB}_1) - R(\overrightarrow{TB}_2)| \rightarrow 0$$



variogram of $R(TB)$ in the 13-D GMI TB space



Retrieval from an a-priori database

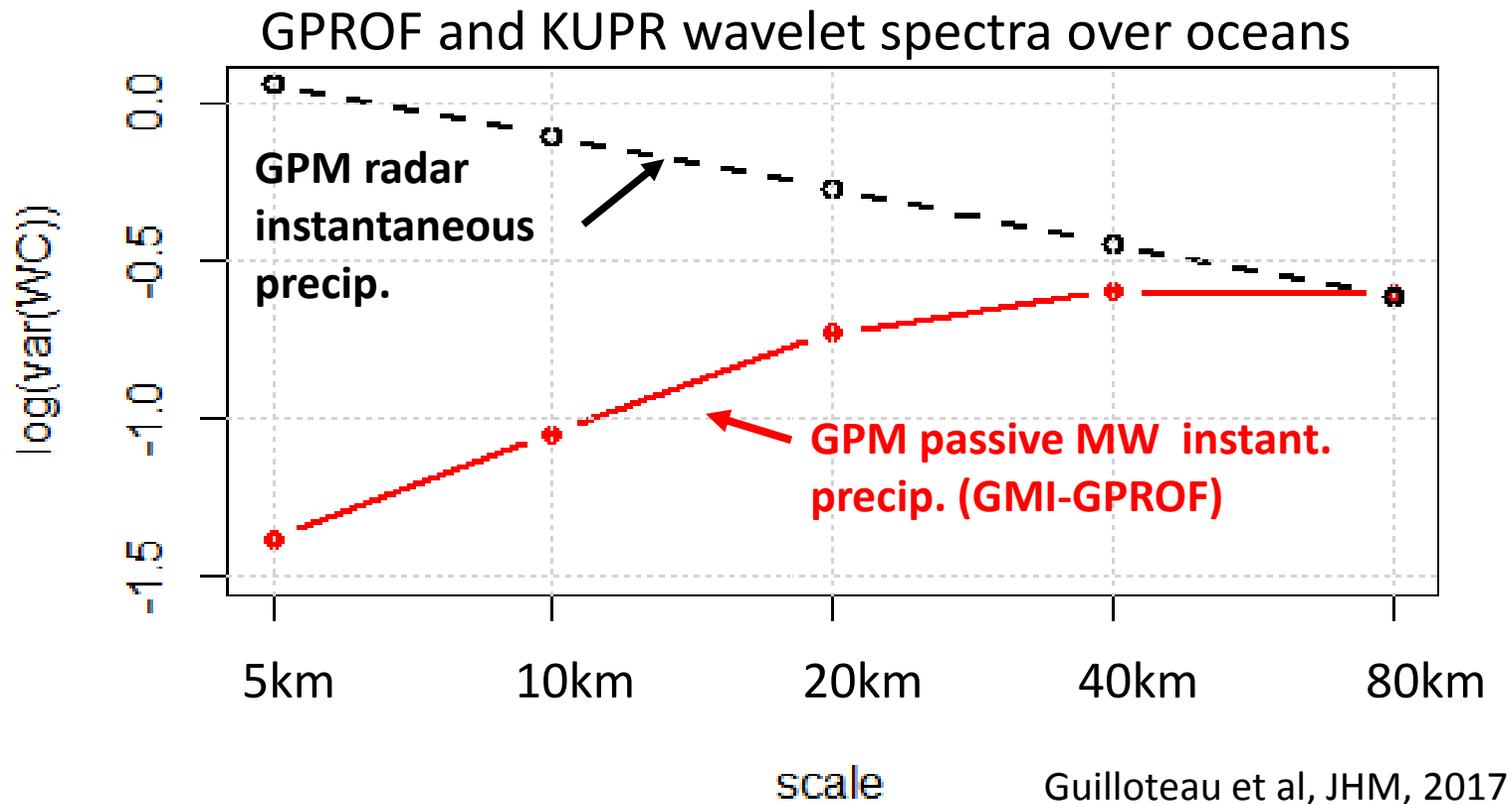
- Irregularity of $R(\overrightarrow{TB}) = \text{large uncertainty}$ on the retrieved R .
- Increasing the density of the database does not help much (because of the nugget effect).
- Choosing a **smooth solution** (average or combination of several profiles of the databases) reduces the mean squared error but ...
... poor performance for the retrieval of extremes.



Retrieval from an a-priori database

- Irregular
- Increased (because)
- Choosing profiles

smooth relations in the TB space = spatially smooth retrieved precipitation fields



R.



Several
it ...



⇒ New information needed to reduce the uncertainty.

Supplementary information ...

... can be obtained from **ancillary datasets**, e.g. surface type, environment parameters from reanalyses (CAPE, TPW, 2-m-temperature ...).

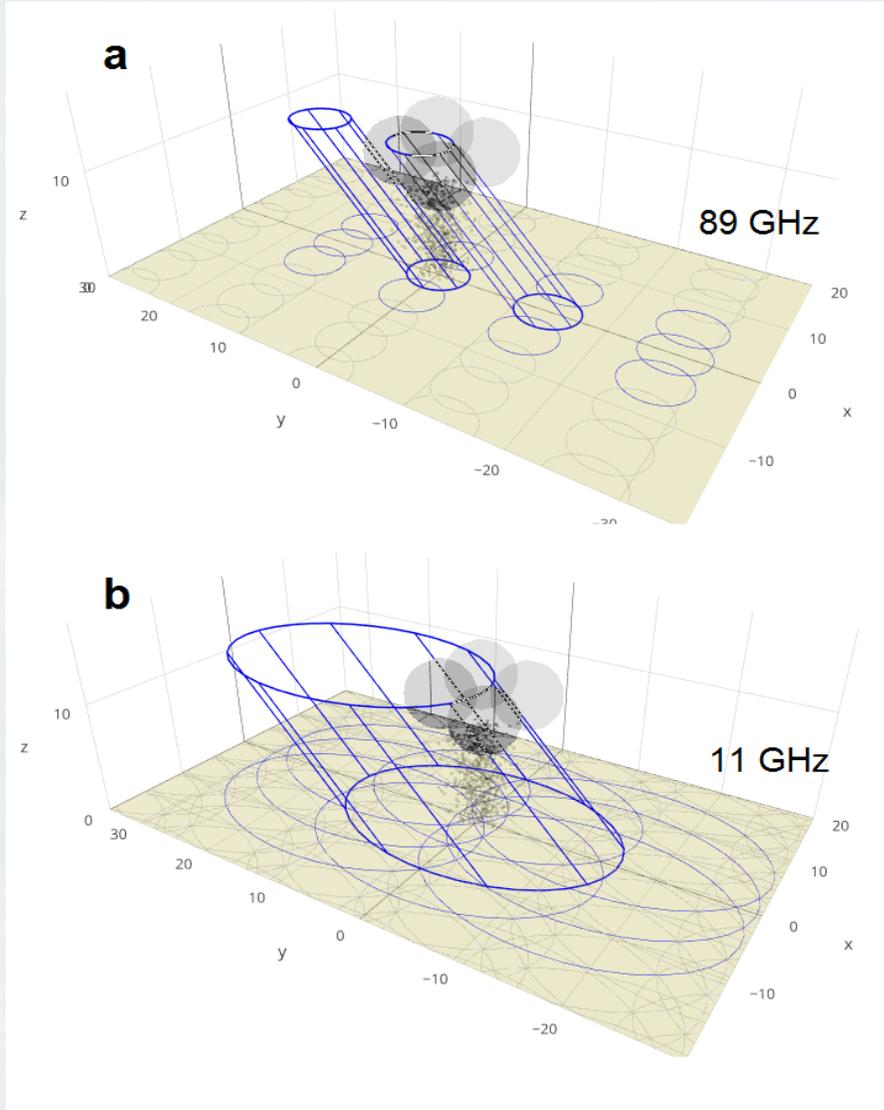
... can be extracted from the **spatial variations of the TBs** in the **neighborhood** around the “pixel” of interest.

⇒ **New paradigm:**

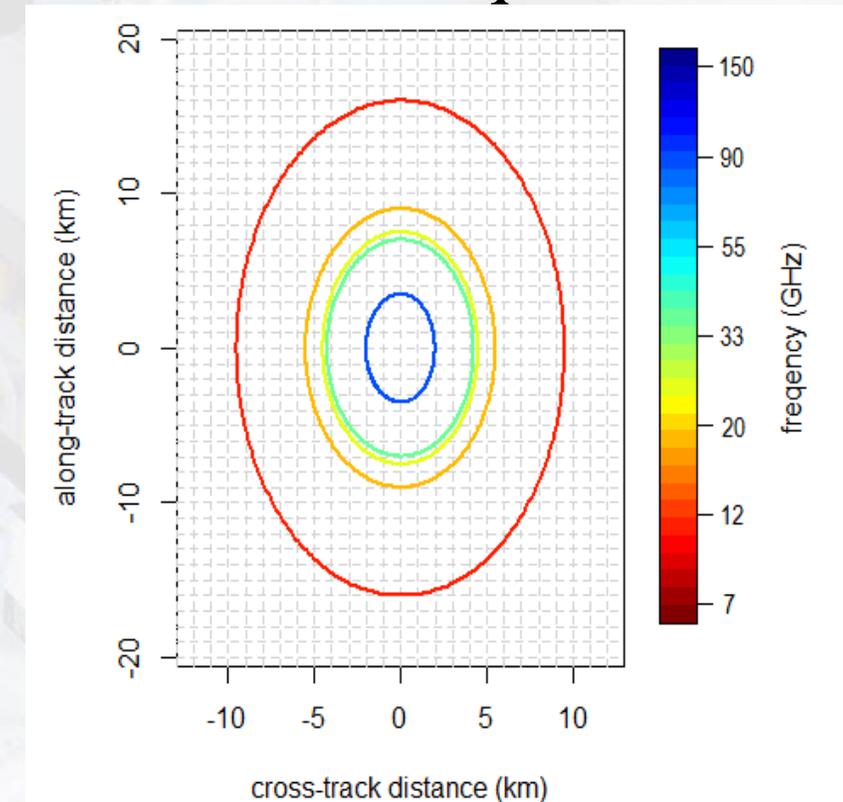
- Current algorithms invert one “pixel” at a time and all “pixels” independently, ignoring the spatial structure of precipitation across adjacent “pixels”.
- **The “nonlocal” approach aims at overcoming the pixel-wise relations between TBs and precipitation.**

Why?: “nonlocal” information in observed TBs

Observation geometry

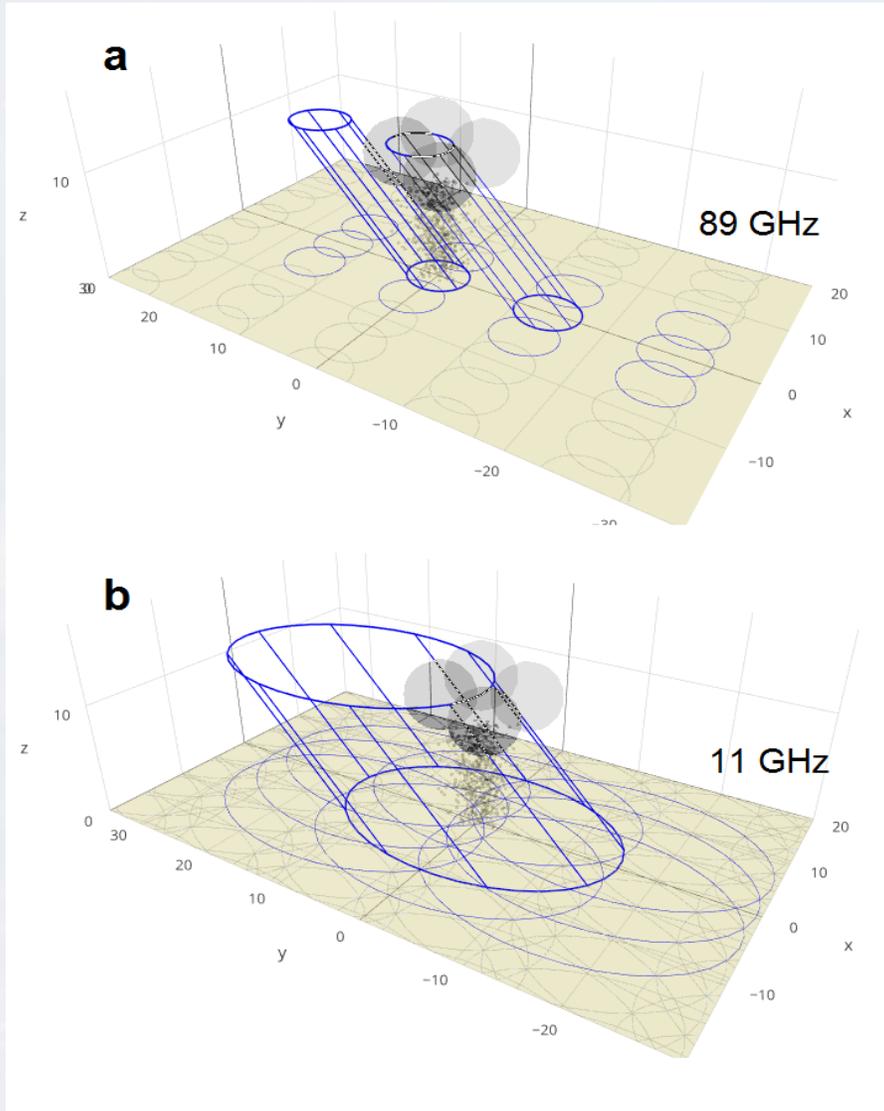


GMI footprints at various frequencies



What is the retrieval field of view? What defines the “pixel” and the retrieval “resolution”?

Observation geometry



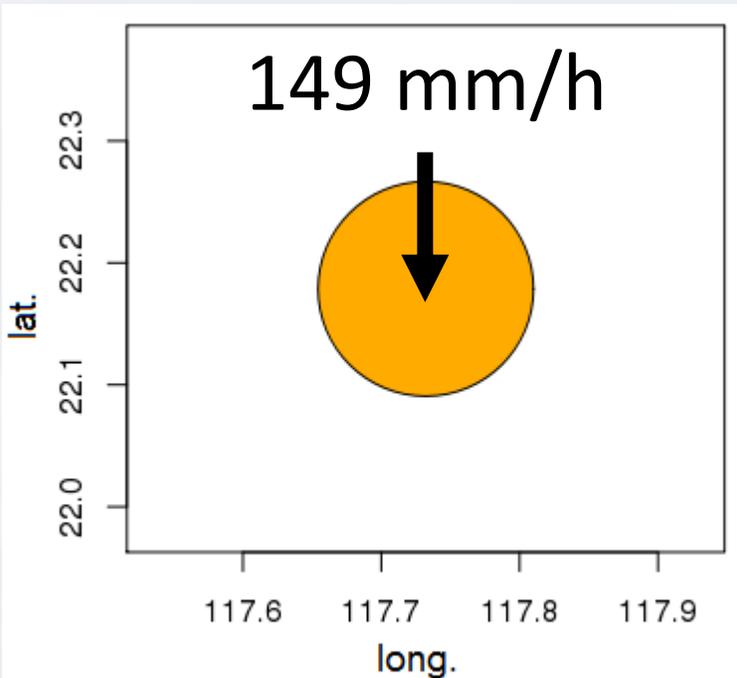
- **Low Frequencies (<40 GHz):** Significant **overlapping** of the fields of view.
- **High Frequencies:** 53° Earth incident angle \Rightarrow a vertical atmospheric column always interpolated by at least two different fields of view.

Different channels responding to different altitude levels \Rightarrow **multi-spectral signature** characterizing a vertical atmospheric column **split across several pixels**.

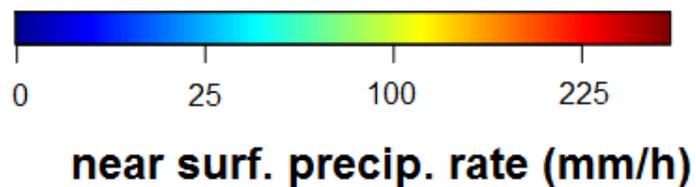
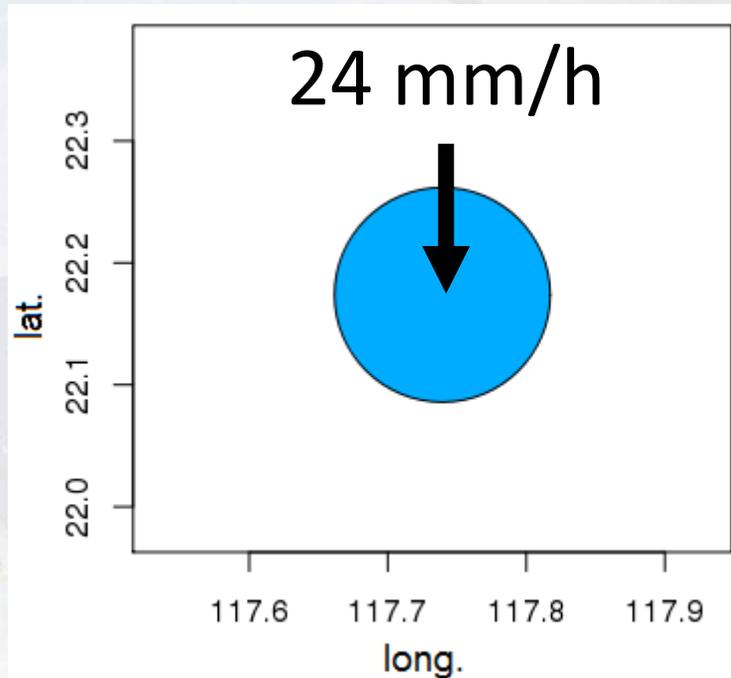
Why?: “nonlocal” information in observed TBs

Illustrative case study:

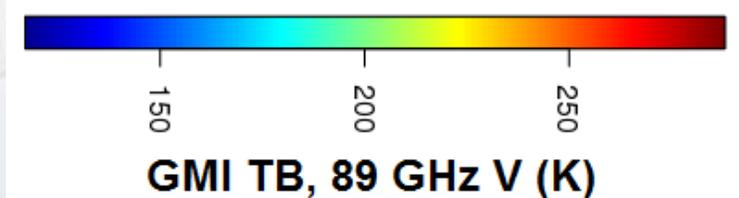
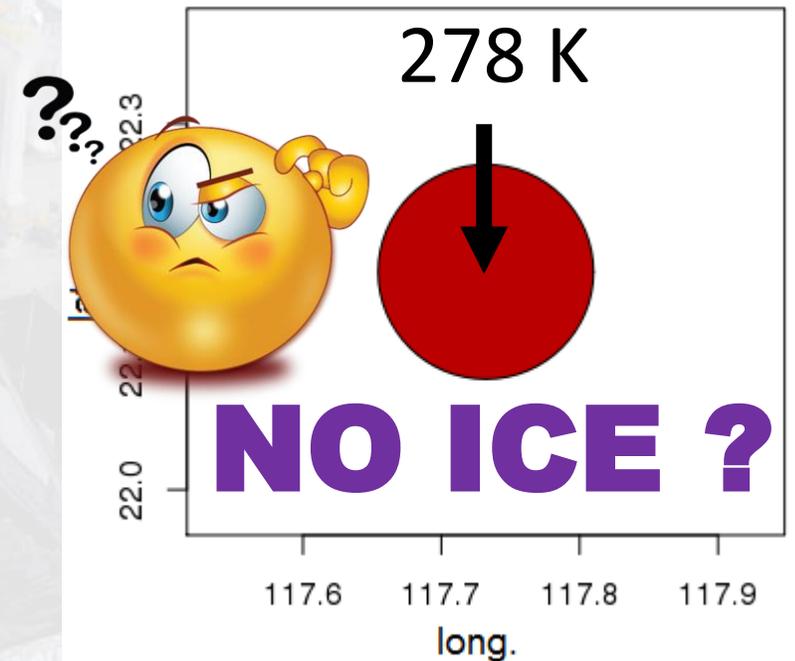
DPR



GMI GPROF



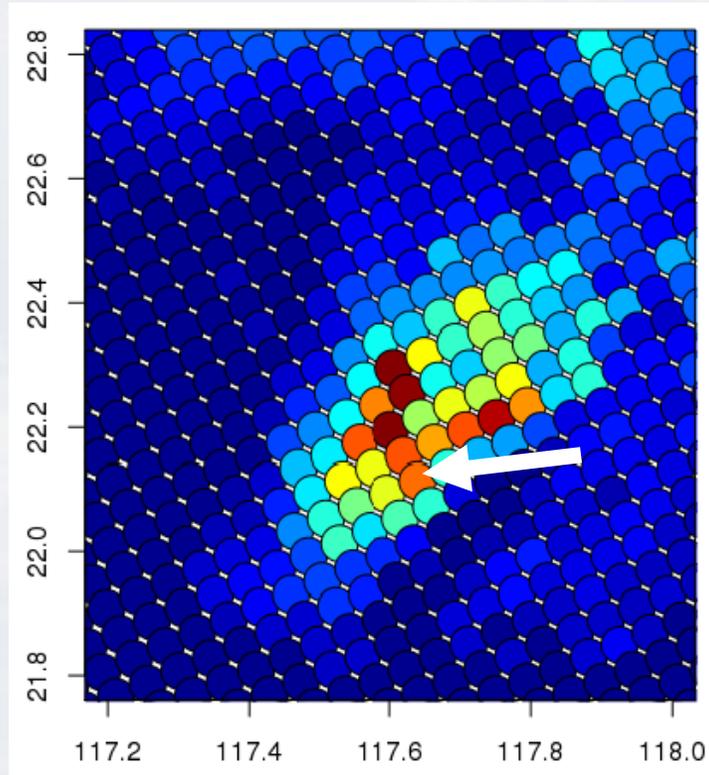
GMI 89 GHz V TB



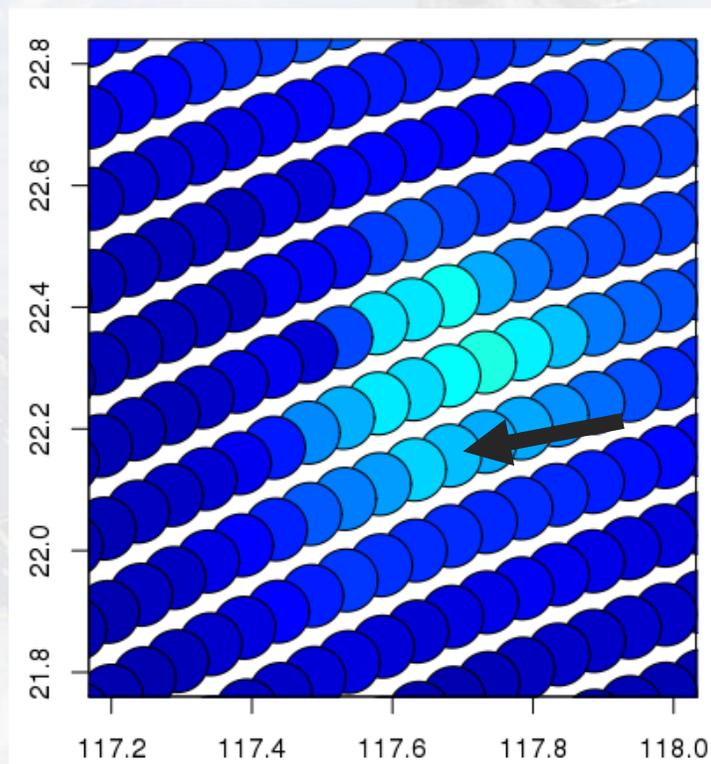
Why?: “nonlocal” information in observed TBs

Illustrative case study:

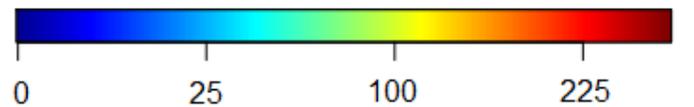
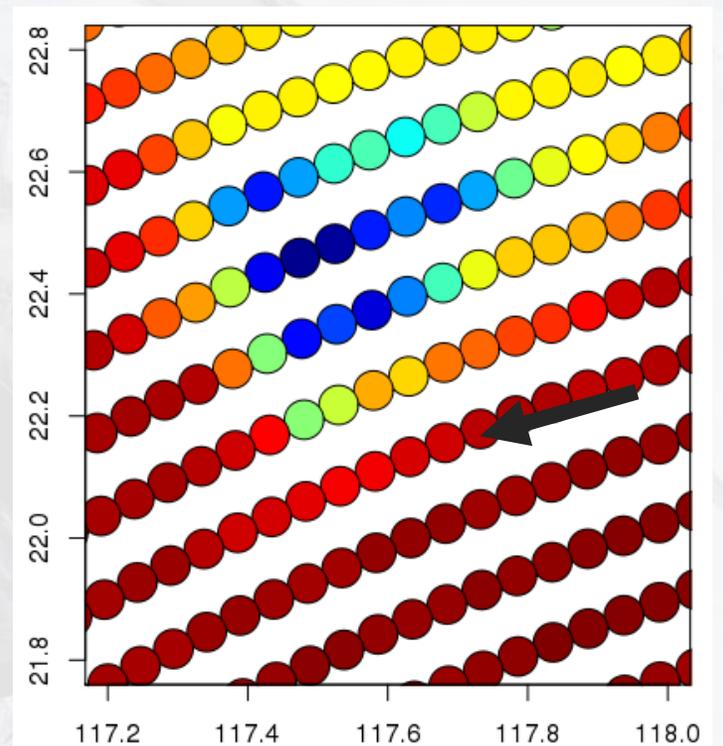
DPR



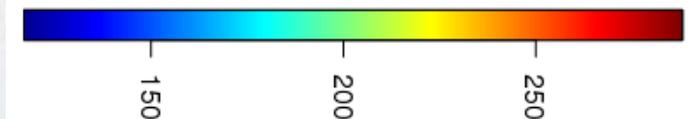
GMI GPROF



GMI 89 GHz V TB



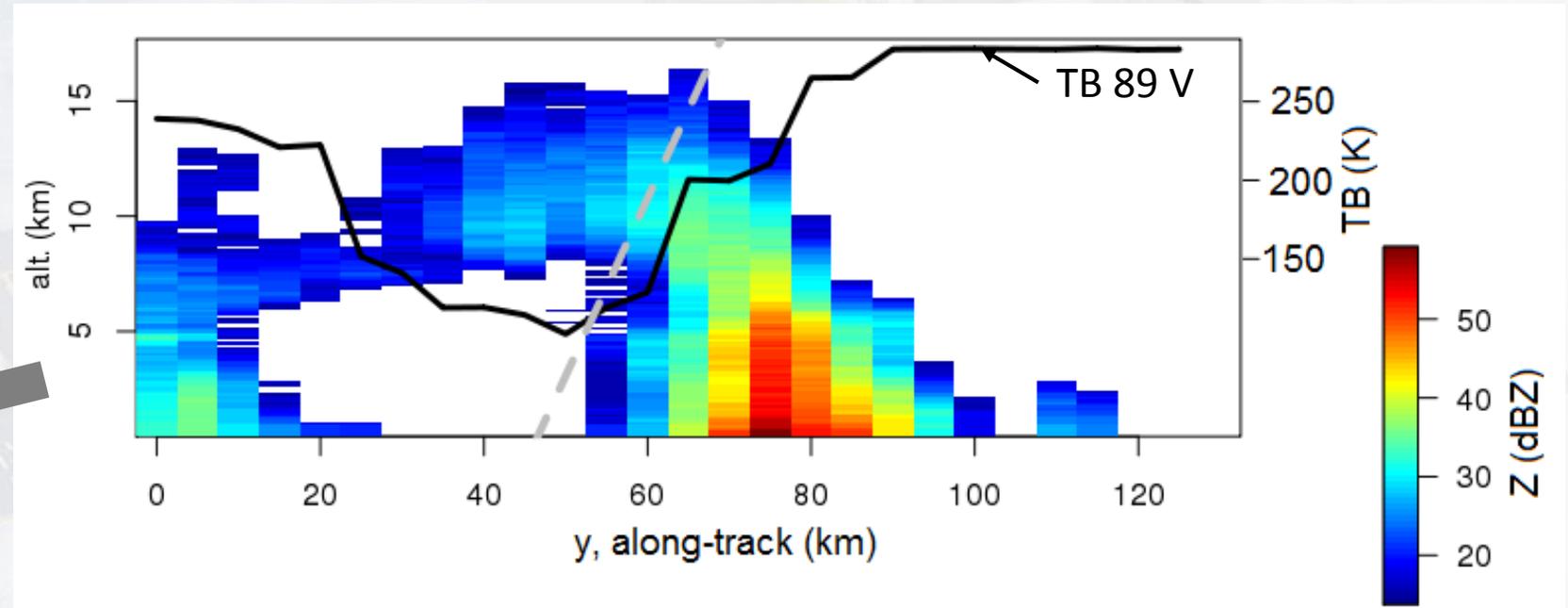
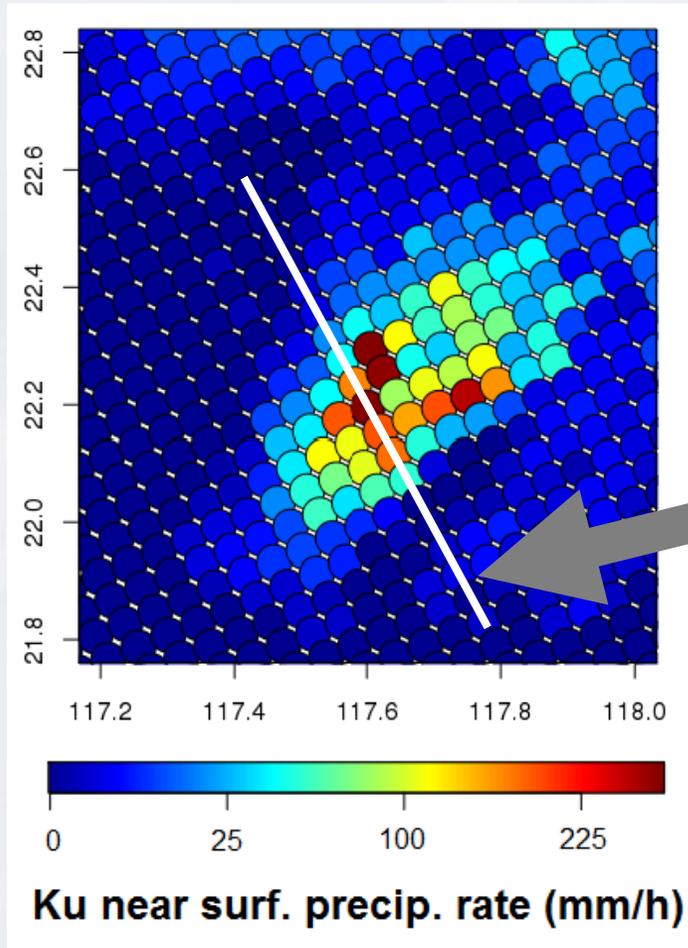
near surf. precip. rate (mm/h)



GMI TB, 89 GHz V (K)

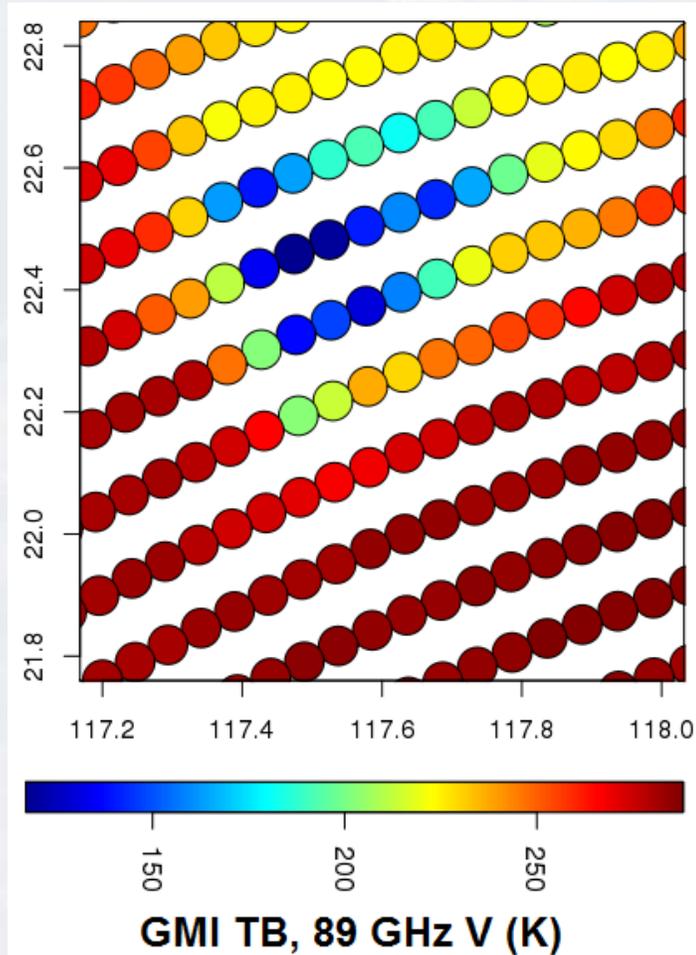
Why?: “nonlocal” information in observed TBs

Three-dimensional structure of the system:

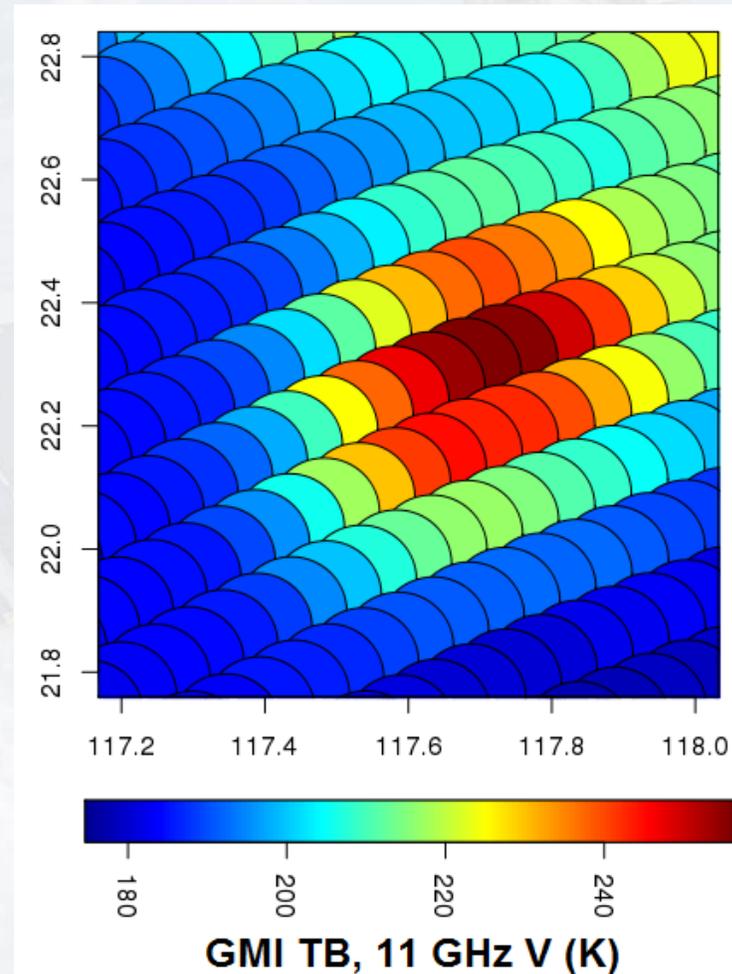


Why?: “nonlocal” information in observed TBs

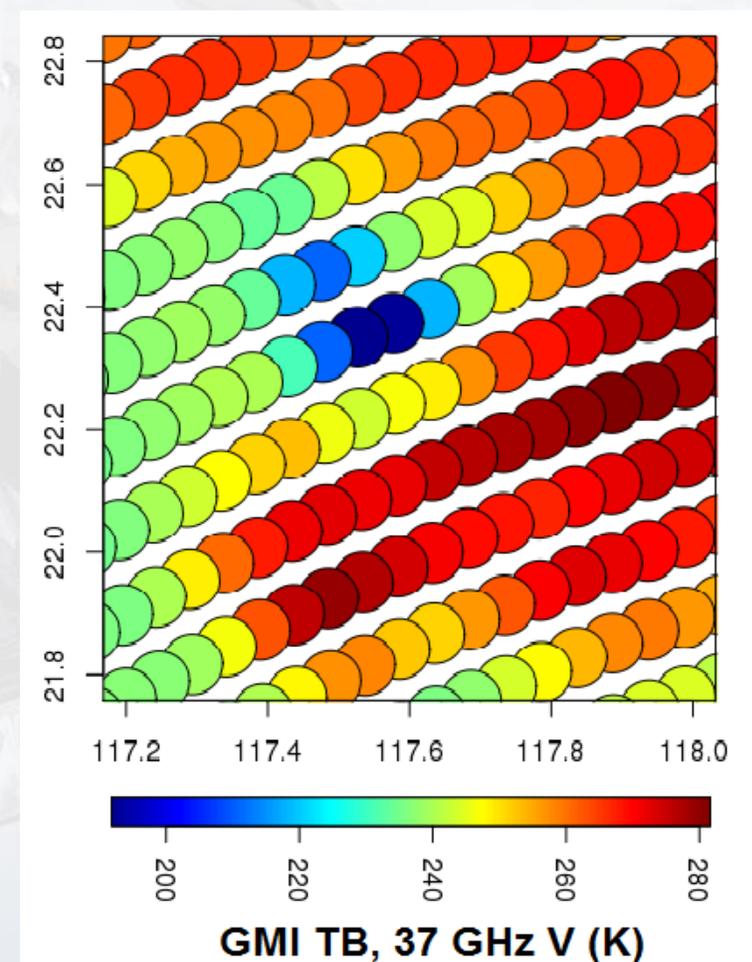
GMI 89 GHz V TB



GMI 11 GHz V TB

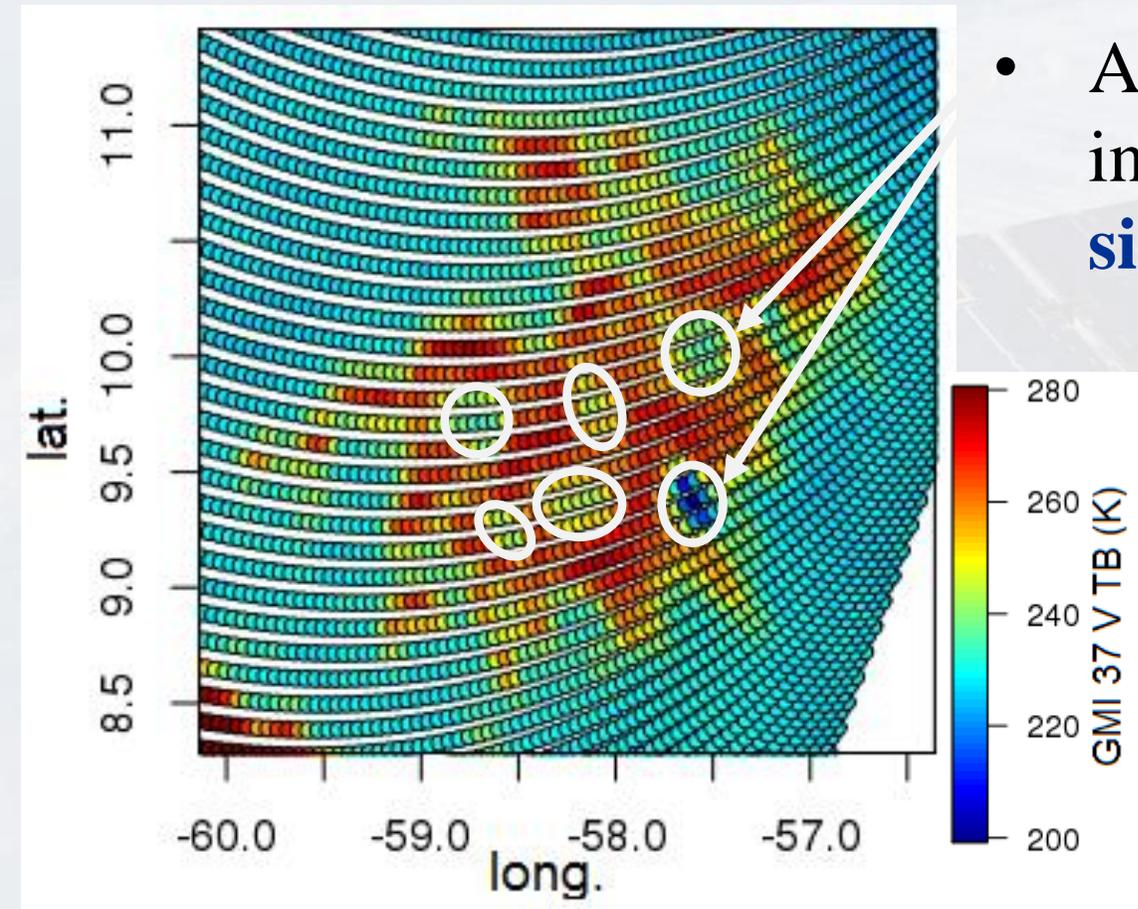


GMI 37 GHz V TB



Why?: “nonlocal” information in observed TBs

- 37 GHz TB sensitive to both liquid emission and ice scattering.
=> Non-monotonic response to precipitation intensity.



- Area with low / medium TBs embedded inside an area of high TBs = **geometric signature** of a convective cell.

- ⇒ **Specific TB patterns are the signatures of specific atmospheric features.**
- ⇒ **Scale dependence in the covariations of TBs and precipitation.**

Why?: “nonlocal” information in observed TBs

relations between TBs 37V and 89V as a function of the scale

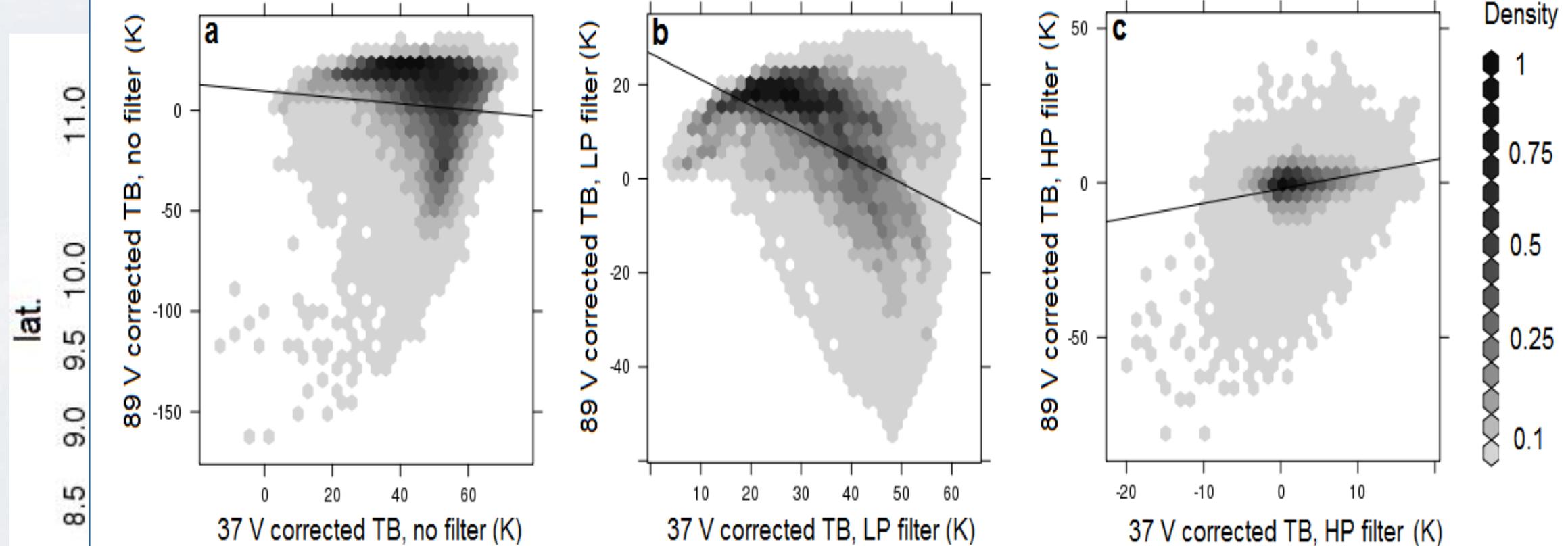
coarse scales

fine scales

all scales

> 100km

< 40 km



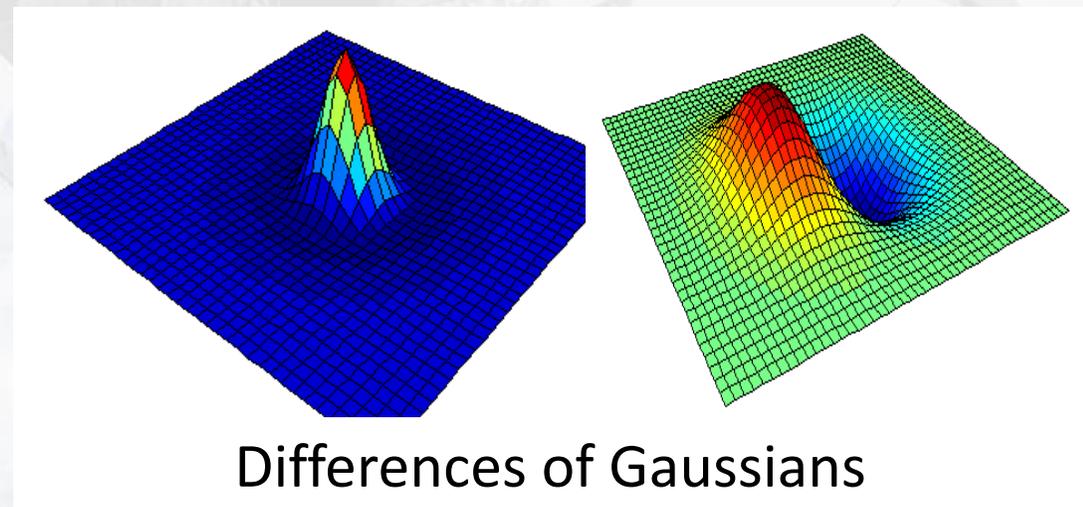
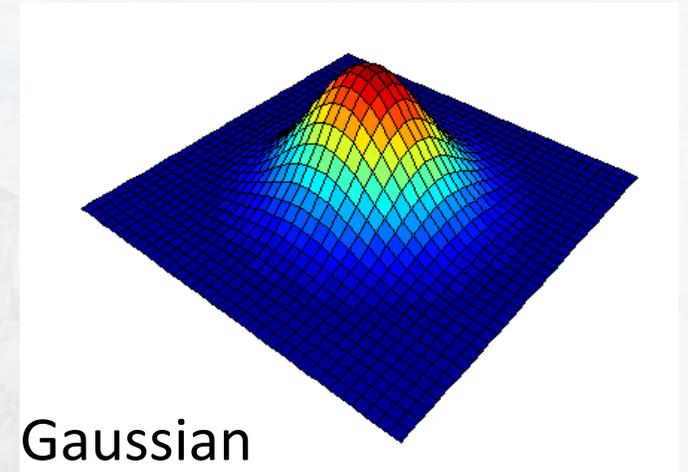
over ocean, TBs corrected from the influence of surface temperature

ures

s of

The spatial variability of the TBs around can be analyzed through **convolution filters**.

- Pattern extraction (with or without directionality parameter)
- Multiscale decomposition of the TB fields (orthogonal filters / wavelets)

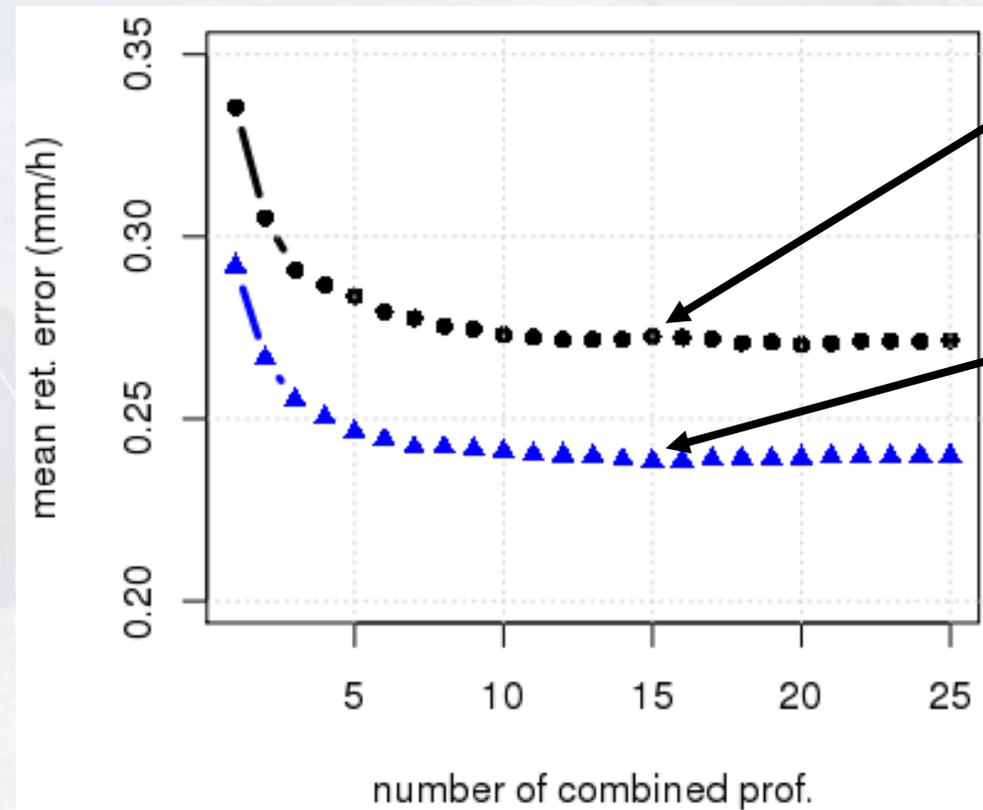


The nonlocal parameters derived from the spatial variations of the TBs can be used in various ways:

- By performing a **pre-selection** of the atmospheric profiles of the a-priori database before the retrieval, i.e. a first classification step.
- By including them in the observation vector to **augment** it and compute the radiometric distances in a **higher-dimensional space** to perform the retrieval.

Preliminary results

Retrieval from GMI over land with a 700 000 - profile a-priori database:



13 "pixel" TBs
+ 2m temp. + surf. type

13 "pixel" TBs
+ 2m temp. + surf. type
+ 3 nonlocal param. (at
37 and 89 GHz)

Conclusions

- Current algorithms perform pixel-wise retrievals associating the precipitation rate in a “pixel” only to the TBs observed inside the pixel.
- But the pixel exists within a context. TB fields have a spatial organization reflecting the spatial organization of precipitation. ⇒ **There is information outside of the pixel.**
 - + With the scanning geometry of GMI and other similar instruments the pixel is ill-defined.
- Information from outside the pixel can be extracted (e.g. using convolution filters) to better constrain the inversion and reduce the retrieval uncertainty.